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Ideal MHD waves and instabilities

Around an equilibrium: \vec{B}_0, P_0, ρ_0 .

Look at the case without equilibrium flow, $\vec{V}_0 = 0$.

Linearize the Ideal MHD Eqs.

$$\frac{\partial \rho_1}{\partial t} + \nabla \cdot (\rho_0 \mathbf{v}_1) = 0 \quad \dots (1)$$

$$\left\{ \begin{array}{l} \rho_0 \frac{\partial \mathbf{v}_1}{\partial t} = -\nabla P_1 + \frac{(\nabla \times \mathbf{B}_1) \times \mathbf{B}_0}{4\pi} + \frac{(\nabla \times \mathbf{B}_0) \times \mathbf{B}_1}{4\pi} \dots (2) \\ \end{array} \right.$$

$$\left. \begin{array}{l} \frac{1}{\rho_0^\gamma} \frac{\partial P_1}{\partial t} - \gamma \frac{P_0}{\rho_0^{\gamma+1}} \frac{\partial \rho_1}{\partial t} + \mathbf{v}_1 \cdot \nabla \frac{P_0}{\rho_0^\gamma} = 0 \end{array} \right. \dots (3)$$

$$\left. \begin{array}{l} \frac{\partial \mathbf{B}_1}{\partial t} = \nabla \times (\mathbf{v}_1 \times \mathbf{B}_0) \end{array} \right. \dots (4)$$

$$\text{Let } v_i = \frac{\partial \xi(x, t)}{\partial t}$$

$$(1) \Rightarrow \dot{\xi}_i = -\nabla \cdot (\xi_0 \xi)$$

$$\begin{aligned} (3) \Rightarrow P_i &= -\frac{\partial P_0}{\xi_0} \nabla \cdot (\xi_0 \xi) - \xi_0^2 \cdot \xi_0 \cdot \nabla \frac{P_0}{\xi_0} \\ &= -\partial P_0 \nabla \cdot \xi - \xi \cdot \nabla P_0 \end{aligned}$$

$$(4) \Rightarrow B_i = \nabla \times (\xi \times B_0)$$

$$\boxed{\xi \frac{\partial^2 \xi}{\partial t^2} = F(\xi)}$$

↓ + ②

Drop Subscript "0"
 for Equilibrium field

$$F(\xi) \equiv \frac{1}{4\pi} (\nabla \times B) \times B_i + \frac{1}{4\pi} (\nabla \times B_i) \times B + \nabla (\xi \cdot \nabla P + \partial P \nabla \cdot \xi)$$

(5)

Waves in homogeneous a plasma

$$B_0 = \text{const}$$

$$P_0 = \text{const}$$

$$\rho_0 = \text{const},$$

$$(B_1, \xi) \propto e^{i(\vec{k} \cdot \vec{x} - wt)}$$

$$B_1 = i \kappa \times (\xi \times B) = i \xi (\kappa \cdot B) - i B (\kappa \cdot \xi)$$

$$(\nabla \times B_1) \times B = i B_1 (\kappa \cdot B) - i \kappa (B_1 \cdot B)$$

$$= -(\kappa \cdot B)^2 \xi + (\kappa \cdot B)(B \kappa) \cdot \xi + \kappa \cdot B (B \kappa) \xi \\ - B^2 (\kappa \kappa) \xi$$

$$\nabla \sigma P \nabla \cdot \xi = -\sigma P (\kappa \kappa) \cdot \xi$$

$$\text{Eq (5)} \Rightarrow \left\{ \begin{array}{l} \left[\omega^2 - (\kappa \cdot V_A)^2 \right] \vec{I} - (V_A^2 + V_s^2) \vec{k} \vec{k} \\ + (\kappa \cdot V_A) (\vec{V}_A \vec{k} + \vec{k} \vec{V}_A) \end{array} \right\} \vec{\xi} = 0$$

Where

$$\vec{V}_A = \frac{\vec{B}}{\sqrt{4\pi g}}, \quad V_s = \sqrt{\sigma P/g}$$

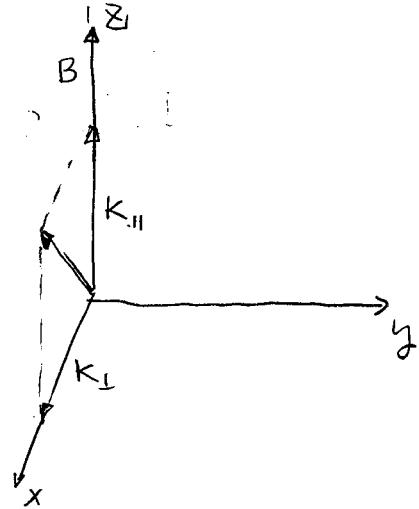
(6)

choose

$$\vec{B} = B \hat{z}$$

$$\vec{k} = k_z \hat{z} + k_x \hat{x}$$

$$= \begin{matrix} \parallel \\ k_{\parallel} \end{matrix} \quad \begin{matrix} \parallel \\ k_{\perp} \end{matrix}$$



In matrix form Eq ⑥ is:

$$\begin{pmatrix} \omega^2 - k_x^2 (V_A^2 + V_s^2) - k_z^2 V_A^2 & 0 & -k_x k_z V_s^2 \\ 0 & \omega^2 - k_z^2 V_A^2 & 0 \\ -k_x k_z V_s^2 & 0 & \omega^2 - k_z^2 V_s^2 \end{pmatrix} \begin{pmatrix} \xi_x \\ \xi_y \\ \xi_z \end{pmatrix} = 0$$

The ξ_y is decoupled!

$$\det = 0$$

$$\Rightarrow (\omega^2 - k_z^2 V_A^2) \left[\left[\omega^2 - k_{\perp}^2 (V_A^2 + V_s^2) - k_{\parallel}^2 V_A^2 \right] : \left(\omega^2 - k_{\parallel}^2 V_s^2 \right) \right] = 0$$

$$- k_{\perp}^2 k_{\parallel}^2 V_s^4$$

$$\Rightarrow (\omega^2 - k_z^2 V_A^2) \left[\omega^4 - k^2 (V_A^2 + V_s^2) \omega^2 + k_{\parallel}^2 k_{\perp}^2 V_A^2 V_s^2 \right] = 0$$

$$\omega^2 = \kappa_{\parallel}^2 V_A^2 \quad \text{Shear Alfvén wave}$$

$$\left(\frac{\omega}{\kappa}\right)^2 = \frac{(V_A^2 + V_S^2) \pm \sqrt{(V_A^2 + V_S^2)^2 - 4\left(\frac{\kappa_{\parallel}}{\kappa}\right)^2 V_A^2 V_S^2}}{2}$$

Fast (+)
 & magneto-sonic wave
 Slow (-)

NO instability and damping for homogeneous
 plasmas in ideal MHD

Kinetic theory or Non-ideal MHD is needed

for instability or damping associated with

velocity-space inhomogeneities, such as

temperature anisotropy instability, two-stream

instability, and Landau damping.

Energy Principle for General Equilibrium

- For the linearized MHD Eq (5).
- But, we start from the nonlinear energy conservation
 & the Lagrangian coordinate

$$\left\{ \begin{array}{l} \Sigma = \frac{1}{2} \int_V \rho v^2 d^3x + \int_V \left(\frac{P}{\gamma-1} + \frac{B^2}{8\pi} \right) d^3x \\ \frac{d\Sigma}{dt} = 0 \end{array} \right.$$

$$x = x(x_0, t) = x_0 + \xi(x_0, t)$$

↑
 Lagrangian
 coordinate

(V, S, P, B) are functions of ξ

Section 3
 variational
 principles

$$v = \left. \frac{\partial \xi}{\partial t} \right|_{x_0} \quad (10)$$

$$\rho = \rho_0(x_0) / J$$

$$J = \det \left| I + \frac{\partial \xi_i(x_0, t)}{\partial x_{0i}} \right| \quad (11)$$

(12)

$$P = P_0(x_0) / \gamma^r$$

$$B_i = \frac{B_{0m}}{\gamma} \left[S_{mi} + \frac{\partial \xi_m(x_0, t)}{\partial x_{0i}} \right] \quad (13)$$

Taylor expansion of ϵ in terms of small ξ

$$\epsilon = \epsilon_0 + \epsilon_1 + \epsilon_2 + \dots = \text{const}$$

$$\epsilon_0 = \frac{1}{2} \int_V \left(\frac{P_0}{\gamma-1} + \frac{B_0^2}{8\pi} \right) d^3x = \text{const}$$

$$\epsilon_1 = \frac{1}{2} \int_V \left[\frac{P_1}{\gamma-1} + \frac{B_0 \cdot B_1}{4\pi} \right] d^3x$$

$$= \frac{1}{2} \int_V \left[\frac{-\gamma P_0 \nabla \cdot \xi - \xi \cdot \nabla P_0}{\gamma-1} + \frac{B_0 \cdot \nabla \times (\xi \times B_0)}{4\pi} \right] d^3x$$

||

||

$$\underbrace{(\gamma-1) \xi \cdot \nabla P_0 - \gamma \nabla \cdot (\xi P_0)}_{\gamma-1} - \frac{1}{4\pi} \left(\begin{array}{l} \nabla \cdot (\xi \times B_0 \times B_0) \\ + (\xi \times B_0) \cdot \nabla \times B_0 \end{array} \right)$$

$$= \frac{1}{2} \int_V \xi \cdot \left(\nabla P_0 + \frac{B \times \nabla \times B_0}{4\pi} \right) d^3x + \frac{1}{2} \int_V \nabla \cdot \left(\frac{\xi \times B_0 \times B_0}{4\pi} - \frac{\gamma \xi P_0}{\gamma-1} \right) d^3x$$

||
0

= 0

$$\Sigma_2 = \int_V g_0 \left(\frac{\partial \xi}{\partial t} \right)^2 d^3x + W_2(\xi, \xi)$$

↑ (14)

linear on both arguments.

The Expression for $W_2(\xi, \xi)$ can be given from Eqs. (10) - (13), but it's complicated. But we can express $W_2(\xi, \xi)$ in terms of $F(\xi)$.

$$\frac{d\Sigma}{dt} = \frac{d(\Sigma_0 + \Sigma_1 + \Sigma_2 + \dots)}{dt} = \frac{d(\Sigma_2 + \Sigma_3 + \dots)}{dt} = 0$$

$$\left(\frac{d\Sigma}{dt} \right) = \left(\frac{d\Sigma}{dt} \right)_0 + \left(\frac{d\Sigma}{dt} \right)_1 + \left(\frac{d\Sigma}{dt} \right)_2 + \left(\frac{d\Sigma}{dt} \right)_3 + \dots = 0$$

$O(\xi)$ $O(\xi)$ $O(\xi^2)$

$$\Rightarrow \left(\frac{d\Sigma}{dt} \right)_i = 0 \quad (i=0, 1, 2, \dots)$$

Note: $\left(\frac{d\Sigma}{dt} \right)_i \neq \frac{d\Sigma_i}{dt}$

For example, $\frac{d\Sigma_2}{dt}$ contains $O(\xi^3), O(\xi^4) \dots$ terms

$$\frac{d\mathcal{E}_2}{dt} = \int \mathcal{G}_0 \left(\frac{\partial \xi}{\partial t} \right) \frac{\partial^2 \xi}{\partial t^2} d^3x + w_2 \left(\frac{\partial \xi}{\partial t}, \xi \right) + w_2 \left(\xi, \frac{\partial \xi}{\partial t} \right)$$

$$\mathcal{G}_0 \frac{\partial^2 \xi}{\partial t^2} = F(\xi) + F_2(\xi) + F_3(\xi) + \dots$$

\uparrow \uparrow \uparrow
 $O(\xi^2)$ $O(\xi^3)$ $O(\xi^3) + \dots$

(14.1)

$$\Rightarrow \frac{d\mathcal{E}_2}{dt} = O(\xi^2) + O(\xi^3) + \dots$$

$$\begin{aligned} \left[- \left(\frac{d\mathcal{E}}{dt} \right)_2 = \left(\frac{d\mathcal{E}_2}{dt} \right)_2 \right. \\ = \int \frac{\partial \xi}{\partial t} F(\xi) d^3x + w_2 \left(\frac{\partial \xi}{\partial t}, \xi \right) + w_2 \left(\xi, \frac{\partial \xi}{\partial t} \right) \\ \left. = 0 \quad \boxed{14.5} \right] \end{aligned}$$

This is true at any t . At $t=0$, we can pick

$$\text{any function } \eta \equiv \frac{\partial \xi}{\partial t} \sim O(\xi)$$

$$\Rightarrow \boxed{\int_V \eta F(\xi) d^3x + w_2(\eta, \xi) + w_2(\xi, \eta) = 0}$$

(15)

Eg. (15) \Rightarrow Two important Results

- Expression for $W_2(\xi, \xi)$ in terms of $F(\xi)$

$$\frac{1}{2} \int_V \xi F(\xi) d^3 V = -W_2(\xi, \xi) \quad \dots \quad (16)$$

- $F(\xi)$ is self-adjoint.

$$\int_V \eta F(\xi) d^3 x = \int \xi F(\eta) d^3 x \quad \dots \quad (17)$$

Eg. (14.5) \Rightarrow Linear Energy Conservation.

$$\mathcal{E}_1 \equiv \int_V \frac{1}{2} S_0 \left(\frac{\partial \xi}{\partial t} \right)^2 d^3 x - \int_V \frac{1}{2} \xi F(\xi) d^3 x = \text{const.} \quad \dots \quad (18)$$

where ξ satisfies Eg (5).

$$S_0 \frac{\partial^2 \xi}{\partial t^2} = F(\xi) \quad \dots \quad (5)$$

Note: $\mathcal{E}_1 \neq \mathcal{E}_2$, The ξ in \mathcal{E}_2 satisfies Eg. (14.1)

$$\delta K(\xi, \eta) \equiv \frac{1}{2} \int_V f_0 \frac{\partial \xi}{\partial t} \cdot \frac{\partial \eta}{\partial t} d^3x$$

$$\delta W(\xi, \eta) \equiv -\frac{1}{2} \int_V \xi \cdot F(\eta) d^3x$$

$$E_f = \delta K(\xi, \xi) + \delta W(\xi, \xi) = \text{const}$$

(18)

Eq. (18) \Rightarrow Energy Principle

Eq. (5) is stable $\iff \delta W(\xi, \xi) > 0$ for any real ξ satisfying B.C.

Proof:

(i) Eq. (5) is stable $\iff \delta W(\xi, \xi) > 0$ for any real ξ .

otherwise, Eq. (5) has an unstable eigenmode

$$\xi = \xi_x e^{-i\omega t} \quad \text{with} \quad \gamma \equiv \text{Im}(\omega) > 0$$

$$\text{Let } \eta = \frac{1}{2}(\bar{\xi} + \xi) = e^{i\omega t} \text{Re}[\xi_x e^{-i\omega_r t}]$$

obviously η is a solution of Eq. (5)

Eq (18) \Rightarrow

$$\delta W(\eta, \eta) = \text{const} - \delta K(\eta, \eta)$$

$$\delta K(\eta, \eta) = \frac{1}{2} \int_V \rho_0 \left(\frac{\partial \eta}{\partial t} \right)^2 d^3x = \text{const} e^{2\gamma_0 t}$$

grows without bound

$\Rightarrow \delta W(\eta, \eta) < 0$ when t is big enough. \blacksquare

(ii) Eq. (5) has an unstable solution $\Leftrightarrow \delta W(\xi, \xi) < 0$ for a real ξ

Let $\delta W(\xi_0, \xi_0) < 0$ for a real ξ_0 ,

Define. $\gamma_0^2 \equiv - \frac{\delta W(\xi_0, \xi_0)}{\frac{1}{2} \int_V \rho \xi_0^2 d^3x} > 0$ (18)

$\parallel \delta K(\xi_0, \xi_0)$

let $\xi(t=0) = \xi_0$ and $\frac{d\xi}{dt}(t=0) = \gamma_0 \xi_0$,

and we now prove

$$\delta K(\xi, \xi) \equiv \frac{1}{2} \int_V \rho \xi^2 d^3x \geq \delta K(\xi_0, \xi_0) e^{2\gamma_0 t},$$

which means $\xi(t)$ is an unstable solution with a

growth rate $\geq 2\gamma_0$.

$$\frac{d \delta k(\xi, \xi)}{dt} = \int_V \xi \cdot \frac{\partial \xi}{\partial t} \rho d^3x$$

$$\frac{d^2}{dt^2} \delta k(\xi, \xi) = \int_V \left[\rho \left(\frac{\partial \xi}{\partial t} \right)^2 + \xi \cdot F(\xi) \right] d^3x$$

$$= 2 \left[\delta k \left(\frac{\partial \xi}{\partial t}, \frac{\partial \xi}{\partial t} \right) - \delta w(\xi, \xi) \right]$$

$$= 2 \left[2 \delta k \left(\frac{\partial \xi}{\partial t}, \frac{\partial \xi}{\partial t} \right) + \varepsilon_2 \right],$$

Eq. (17)

Eq. (18)

$$\text{where } \varepsilon_2 = \delta k \left(\frac{\partial \xi}{\partial t}, \frac{\partial \xi}{\partial t} \right) + \delta w(\xi, \xi)$$

$$= \left[\delta k \left(\frac{\partial \xi}{\partial t}, \frac{\partial \xi}{\partial t} \right) + \delta w(\xi, \xi) \right] \Big|_{t=0} = 0$$

$$(\delta k)^2 = \left[\int_V d^3x \rho (\xi \cdot \frac{\partial \xi}{\partial t}) \right]^2 \leq \left[\int_V d^3x \rho (\xi^2) \right] \left[\int_V d^3x \rho \left(\frac{\partial \xi}{\partial t} \right)^2 \right]$$

$$= \delta k \delta k$$

Schwarz
inequality

$$\Rightarrow \dot{\delta K} - (\dot{\delta K})^2 \geq 0$$

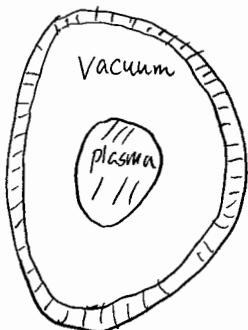
$$\Rightarrow \frac{d}{dt} \left(\frac{\dot{\delta K}}{\delta K} \right) \geq 0 \Rightarrow \frac{\dot{\delta K}}{\delta K} \geq \left(\frac{\dot{\delta K}}{\delta K} \right)_{t=0} = 2\gamma_0$$

$$\Rightarrow \delta K \geq e^{2\gamma_0 t} \delta K|_{t=0} \quad \square$$

What is the B.C.?

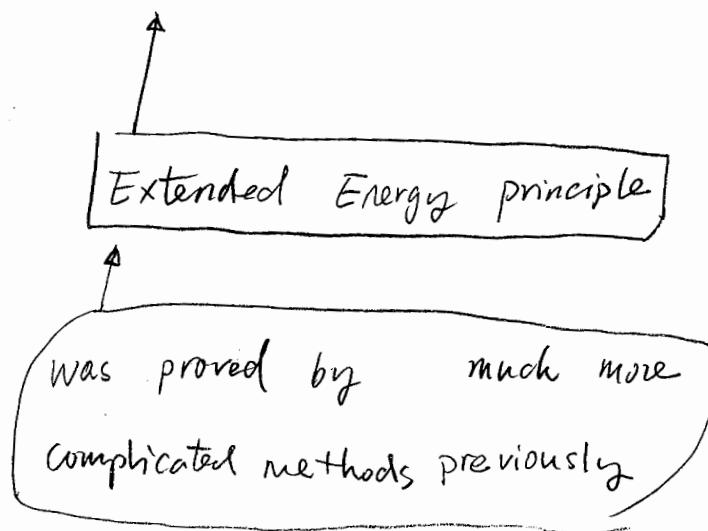


↓
Including plasma - vacuum - wall B.C. as
special cases



'Vacuum' can be treated as
plasma with $\rho_0 = 0$

IF vacuum region exists, the integration domain \mathcal{V} in the energy principle can be replaced by the plasma domain only, Because the \mathcal{V} in $\int_{\mathcal{V}} d^3x$ of Eq(17) can be replaced by the plasma domain.



For the purpose of using harmonic eigenmodes, we note

$$SW(\xi, \xi) > 0 \text{ for any real } \xi$$



$$SW(\eta^*, \eta) > 0 \text{ for any complex } \eta$$

Proof

(i); $SW(\eta^*, \eta) > 0 \text{ for any complex } \eta$



Obviously

$$SW(\xi, \xi) > 0 \text{ for any real } \xi$$

(ii)

$$SW(\eta^*, \eta) = SW(\eta_R, \eta_R) + SW(\eta_I, \eta_I)$$

$$- i SW(\eta_I, \eta_R) + i SW(\eta_R, \eta_I)$$

$$= SW(\eta_R, \eta_R) + SW(\eta_I, \eta_I)$$

self adjointness

$$SW(\eta_I, \eta_R) = SW(\eta_R, \eta_I)$$

Therefore, $SW(\xi, \xi) > 0 \text{ for any real } \xi$



$$SW(\eta^*, \eta) > 0 \text{ for any complex } \eta$$



Different Forms for $\operatorname{sw}(\xi^*, \underline{\xi})$

$$SW(\xi^*, \xi) = -\frac{1}{2} \int_V \xi^* \cdot \left[\frac{1}{4\pi} (\nabla \times B) \times B_1 + \frac{1}{4\pi} (\nabla \times B_1) \times B \right. \\ \left. + \cdot \nabla (\xi \cdot \nabla P) + \nabla (\xi P \nabla \cdot \xi) \right] d^3x \quad \dots (20)$$

$$\begin{aligned}
 (2) &= -\frac{1}{2} \int_V (\nabla \times B_1) \cdot (B \times \xi^*) d^3x = \frac{1}{2} \int_V B_1^2 d^3x - \int_{\partial V} [B_1 \times (B \times \xi^*)] \cdot d\mathbf{s} \\
 &\quad \text{Diagram: A vector } \nabla \cdot [B_1 \times (B \times \xi^*)] \text{ points upwards from the volume integral.} \\
 &\quad \text{Volume integral: } \int_V B \cdot d\mathbf{s} [B_1 \cdot \xi^*] \text{ points outwards from the boundary.} \\
 &\quad \text{Boundary integral: } - \int_{\partial V} \xi^* \cdot d\mathbf{s} [B_1 \cdot B] \text{ points inwards from the boundary.} \\
 &\quad \text{Assume } B \cdot d\mathbf{s} = 0 \text{ (indicated by a circle with a dot).} \\
 &\quad \text{Boundary term: } \xi_L^* \cdot d\mathbf{s} \text{ (indicated by a circle with a dot).} \\
 (4) &= + \frac{1}{2} \int_V \sigma P (\nabla \cdot \xi)^2 d^3x - \frac{1}{2} \int_{\partial V} [\sigma P \nabla \cdot \xi] \xi^* \cdot d\mathbf{s} \\
 &\quad \text{Boundary term: } \xi_L^* \cdot d\mathbf{s} \text{ (indicated by a circle with a dot).}
 \end{aligned}$$

$$\textcircled{1} + \textcircled{3} = -\frac{1}{2} \int_A^* \xi_+^* \left[\frac{1}{4\pi} (\nabla \times B) \times B_1 + \nabla \cdot (\xi \cdot \nabla p) \right] d^3x$$

\uparrow

$b \cdot \left[\frac{\dot{x} \times B_1}{c} + \nabla \cdot (\xi \cdot \nabla p) \right] = 0$

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$$\begin{aligned}
 b \cdot \left[\frac{\partial \times}{c} B_1 \right] &= - \frac{\partial \times \vec{B}}{c B} \cdot B_1 = - \frac{\nabla P}{B} \cdot B_1 \\
 &= - \frac{\nabla P \cdot [\nabla \times (\xi \times B)]}{B} \\
 &= \frac{\nabla \cdot [\nabla P \times (\xi \times B)]}{B} = \frac{\nabla \cdot (\xi \vec{B} \cdot \nabla P - \vec{B} \xi \cdot \nabla P)}{B} \\
 &= - \frac{\vec{B}}{B} \nabla (\xi \cdot \nabla P)
 \end{aligned}$$

$$\begin{aligned}
 ① + ③ &= -\frac{1}{2} \int_V \left[\xi_L^* \cdot \frac{1}{4\pi} (\nabla \times B) \times B_1 \right] d^3x \\
 &\quad + \frac{1}{2} \int_V \underbrace{(\xi \cdot \nabla P)}_{\xi_L \cdot \nabla P} \nabla \cdot \xi_L^* d^3x - \frac{1}{2} \int_{\partial V} \underbrace{[ds \cdot \xi_L^*]}_{\xi_L \cdot \nabla P} \xi \cdot \nabla P
 \end{aligned}$$

$$\delta W = \delta W_F + B.T.$$

$$\delta W_F = \frac{1}{2} \int_V d^3x \left[\frac{B_1^2}{4\pi} - \xi_L^* \cdot \frac{(\nabla \times B) \times B_1}{4\pi} + \nabla P |\nabla \cdot \xi|^2 + \xi_L \cdot \nabla P \nabla \cdot \xi_L^* \right]$$

(21)

$$B.T. = \frac{1}{2} \int_{\partial V} \vec{ds} \cdot \xi_L^* \left[\frac{B_1 \cdot B}{4\pi} - \nabla P \nabla \cdot \xi - \xi_L \cdot \nabla P \right]$$

(22)

Intuitive Form for $\delta W_F(\xi^*, \xi)$

$$\delta W_F = \frac{1}{2} \int_V d^3x \left[\frac{B_1^2}{4\pi} - \xi_\perp^* \cdot \frac{\vec{J} \times \vec{B}_1}{c} + \sigma P |\nabla \cdot \xi|^2 + \xi_\perp \cdot \nabla P \nabla \cdot \xi^* \right]$$

Eliminate $B_{1\parallel}$ using ξ_\perp , and \vec{J}_\perp using P and \vec{B}

$$B_1^2 = B_{1\perp}^2 + B_{1\parallel}^2$$

(i)

$$B_{1\parallel} = b \cdot \nabla \times (\xi_\perp \times \vec{B}) = b \cdot \left(-\vec{B} \nabla \cdot \xi_\perp + \vec{B} \cdot \nabla \xi_\perp \right) \\ - \xi_\perp \cdot \nabla \vec{B}$$

(ii)

$$(i) : b \cdot \left[\vec{B} \cdot \nabla \xi_\perp \right] = \vec{B} \cdot \nabla (b \cdot \xi_\perp) - \left[\vec{B} \cdot \nabla b \right] \cdot \xi_\perp = -B \chi \cdot \xi_\perp$$

$$(ii) : b \cdot \left[\xi_\perp \cdot \nabla \vec{B} \right] = \xi_\perp \cdot \nabla (b \cdot \vec{B}) - \left(\xi_\perp \cdot \nabla \vec{b} \right) \cdot b \vec{B}$$

$$\frac{\xi \chi \vec{B}}{c} = \chi \frac{B^2}{4\pi} - \nabla_\perp \frac{B^2}{8\pi} = \nabla P \Rightarrow \xi_\perp \cdot \left[\chi B - \frac{4\pi \nabla P}{B} \right]$$

$$\Rightarrow B_{1\parallel} = -B \nabla \cdot \xi_\perp - 2B \chi \cdot \xi_\perp + \frac{4\pi}{B} \xi_\perp \cdot \nabla P$$

$$0 = a \cdot \nabla (b \cdot b) = 2(a \cdot \nabla b) \cdot b$$

$$\boxed{\xi_{\perp}^* \cdot \left[\frac{\vec{J} \times \vec{B}_1}{c} \right]} = \frac{\xi_{\perp}^*}{c} \left[\vec{J}_{\perp} \times \vec{B}_{1\parallel} + \vec{J}_{\perp} \times \vec{B}_{1\perp} + \vec{J}_{\parallel} \times \vec{B}_{1\perp} \right]$$

$$= \frac{\xi_{\perp}^* \cdot \vec{J}_{\perp} \times \vec{B}_{1\parallel}}{c} + \frac{\xi_{\perp}^* \cdot \vec{J}_{\parallel} \times \vec{B}_{1\perp}}{c}$$

$$\text{II}$$

$$\xi_{\perp}^* \cdot \frac{\nabla P}{B} \vec{B}_{1\parallel}$$

$$\frac{B_{1\parallel}^2}{4\pi} - \frac{\xi_{\perp}^* \cdot \nabla P}{B} \vec{B}_{1\parallel} = \vec{B}_{1\parallel} \left(\frac{-B \nabla \cdot \xi_{\perp}^* - 2B \vec{k} \cdot \xi_{\perp}^*}{4\pi} \right)$$

$$= \frac{(-B \nabla \cdot \xi_{\perp}^* - 2B \vec{k} \cdot \xi_{\perp}^*)^2}{4\pi} - \frac{1}{B} \xi_{\perp}^* \cdot \nabla P \left(B \nabla \cdot \xi_{\perp}^* + 2B \vec{k} \cdot \xi_{\perp}^* \right)$$

$$\Rightarrow \frac{B_{1\parallel}^2}{4\pi} - \frac{\xi_{\perp}^* \cdot \vec{J}_{\perp} \times \vec{B}_{1\parallel}}{B} + \xi_{\perp}^* \cdot \nabla P \nabla \cdot \xi_{\perp}^*$$

$$= \frac{(B \nabla \cdot \xi_{\perp}^* + 2B \vec{k} \cdot \xi_{\perp}^*)^2}{4\pi} - 2\xi_{\perp}^* \cdot \nabla P \vec{k} \cdot \xi_{\perp}^*$$

\Rightarrow

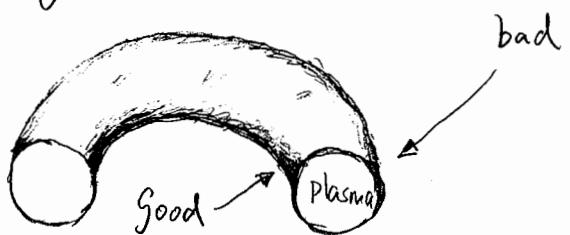
$$\begin{aligned} \textcircled{a} \quad & \delta W_F(\xi^*, \xi) = \frac{1}{2} \int d^3x \left[\frac{B_{\perp}^2}{4\pi} + \frac{\left[B \cdot \nabla \cdot \xi_{\perp} + 2B \cdot k \cdot \xi_{\perp} \right]^2}{4\pi} + \sigma P (\nabla \cdot \xi)^2 \right] \\ \textcircled{b} \quad & - 2(\xi_{\perp} \cdot \nabla P)(k \cdot \xi_{\perp}) - \xi_{\perp}^* \times \vec{J}_{\parallel} \cdot B_{\perp} \end{aligned}$$

Stabilizing

- (a) shear Alfvén, bending
- (b) compressional Alfvén, Compressing
- (c) Sound, compressing
- (d) good curvature, $\nabla P \cdot \lambda < 0$

De-stabilizing

- (d) bad curvature, $\nabla P \cdot \lambda > 0$
- (e) \vec{j}_{\parallel}



Applications of the energy principle

|θ - Pinch|

$$\begin{array}{l} J_{\parallel} = 0 \\ K = 0 \end{array} \Rightarrow \text{stable}$$

Z - pinch

$$\frac{d}{dr} \left(P + \frac{B_\theta^2}{8\pi} \right) + \frac{B_\theta^2}{4\pi r} = 0$$

Strategy: pick ξ to minimize $\delta W(\xi^*, \xi)$

$$\begin{cases} \min(\delta W) > 0 \Rightarrow \text{stable} \\ \delta W < 0 \text{ for some } \xi \Rightarrow \text{unstable} \end{cases}$$

consider $\xi = \vec{\xi}(r) e^{i(m\theta + kz)}$

parallel component ξ_θ only appears in $|\nabla \cdot \xi|^2$,

We can set $|\nabla \cdot \xi| = 0$ to minimize δW with respect to ξ_θ ,

$$\nabla \cdot \xi = 0 \Rightarrow \xi_\theta = \frac{i}{m} [(r \xi_r)' + ik \xi_z] \quad (m \neq 0)$$

$$B_{\perp\perp} = [\nabla \times (\xi \times B)]_+ = \frac{im}{r} B_\theta (\xi_r \hat{e}_r + \xi_z \hat{e}_z)$$

$$\vec{K} = -\frac{\hat{e}_r}{r}$$

$$\vec{J}_{||} = 0$$

$$\nabla \cdot \xi_{\perp} + 2 \xi_{\perp} \cdot k = r \left(\frac{\xi_r}{r} \right)' + ik \xi_z$$

$$\delta W_F (\xi^*, \xi) = \frac{1}{2} 2\pi R_0 \int_0^a w(r) r dr$$

$$W(r) = \frac{m^2 B_\theta^2}{4\pi r^2} (\xi_r^2 + \xi_z^2) + \frac{B_\theta^2}{4\pi} \left| r \left(\frac{\xi_r}{r} \right)' + ik \xi_z \right|^2$$

Minimize
w.r.t ξ_z

$$+ 2 \frac{P'}{r} \xi_r^2$$

$$\left(\frac{m^2 B_\theta^2}{4\pi r^2} + \frac{2P'}{r} \right) \xi_r^2 + \frac{m^2 B_\theta^2}{4\pi (m^2 + k^2 r^2)} \left| \left(\frac{\xi_r}{r} \right)' \right|^2$$

Complete the Square

$$a^2 \xi_z^2 + (b + ik \xi_z)^2 = a^2 \xi_z^2 + b^2 - i b k \xi_z^* + i k \xi_z b^* + k^2 \xi_z^2$$

$$= b^2 - \frac{b^2 k^2}{a^2 + k^2} + \sqrt{\frac{b^2 k^2}{a^2 + k^2} - i b k \xi_z^* + i k \xi_z b^* + (k^2 + a^2) \xi_z^2}$$

$$= b^2 \left[1 - \frac{k^2}{a^2 + k^2} \right] + \left[\frac{b}{\sqrt{a^2 + k^2}} + i \sqrt{k^2 + a^2} \xi_z \right]^2$$

$$= b^2 \left[1 - \frac{k^2}{a^2 + k^2} \right] = \frac{b^2 a^2}{a^2 + k^2} \quad b = r \left(\frac{\xi_r}{r} \right)'$$

minimize

w.r.t ξ_z

$$a^2 = \frac{m^2}{r^2}$$

$$W(r) = \left(\frac{m^2 B_\theta^2}{4\pi r^2} + 2P' \right) \xi_r^2$$

minimize

w.r.t. K

$K \rightarrow \infty$

$$(i) \quad \frac{m^2 B_\theta^2}{4\pi} + 2r P' > 0 \Rightarrow \text{stable}$$

$$(ii) \quad \frac{m^2 B_\theta^2}{4\pi} + 2r P' < 0 \text{ for some } 0 < r_0 < a,$$

\Rightarrow unstable with $\xi_r = \delta(r - r_0)$

Stable Condition (necessary & sufficient)

$$\frac{m^2 B_\theta^2}{4\pi} + 2r P' > 0 \quad + \quad \left. \begin{array}{l} \\ \end{array} \right\} \Rightarrow (m^2 - 2) B_\theta^2 > r (B_\theta^2)'$$

$$P' + \left(\frac{B_\theta^2}{8\pi} \right)' + \frac{B_\theta^2}{4\pi r} = 0$$

Finite current density
 $B_\theta 2\pi r = \frac{4\pi}{c} \pi r^2 J_0$

$$\boxed{m=1} : -B_\theta^2 > r (B_\theta^2)'$$

Not possible near $r \rightarrow 0$, where $B_\theta \propto r$

\Rightarrow Z-pinch unstable for $m=1$

