

# Helical RFP's –Analysis Using Stellarator Tools

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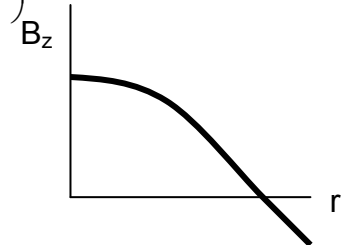
# Helical RFP - good properties - sustainment?

- In axisymmetry, a reversal in  $B_\phi$  cannot be maintained by a  $V_t$

eg. Cylinder, force-free  $\mu_0 \mathbf{J} = k\mathbf{B}$ , current profile  $k(r, t)$

determined by Ohm's law along  $\mathbf{B}$ :  $k(r, t) = \frac{\mu_0}{\eta B^2} \left( \frac{V_p}{2\pi r} B_\theta + \frac{V_t}{2\pi R} B_z \right)$

$dB_z/dr = -kB_\theta \Rightarrow k \neq 0$  where  $B_z$  passes through zero



- A poloidal loop voltage works, but only transiently
- A toroidal loop voltage  $V_t$  plus a helical magnetic field can work, as understood by Ohkawa (1980).
- SHA configurations observed to have good transport properties
- Numerical tools developed for stellarators useful for helical RFP's

# VMEC as a tool for exploring helical RFP's

- Input profiles are EITHER

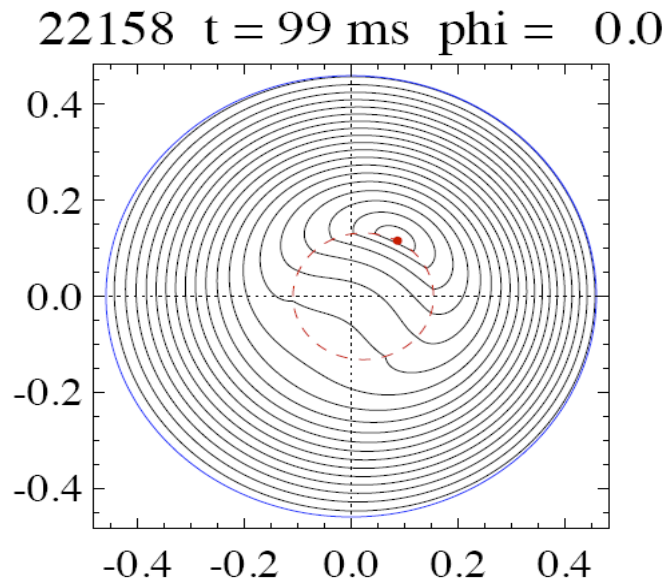
$p(s)$  and  $\iota(s)$  (iota =  $1/q$ ) OR

$p(s)$  and  $k_0(s)$  where  $k_0 = \langle J \cdot B \rangle / \langle B \cdot B \rangle |_{\rho=0} = I'$  AND

outer boundary shape if running “fixed boundary”, or external fields from coils if running “free boundary”

- Also need initial guess (typically crude) for  $\psi (R, \phi, Z)$
- Radial variable,  $s$ , is normalized toroidal flux  $\Rightarrow$  field reversal with standard version impossible, however fix is simple (Hirshman)
- Output is  $\psi (R, \phi, Z)$  and  $k(s)$  OR  $\psi (R, \phi, Z)$  and  $\iota(s)$
- VMEC assumes “good” flux surfaces, so must generate singular currents to shield out any islands that may be present

# VMEC – applied to model of RFX SHA x



⇐ RFX SHA x reconstruction

From “Helical equilibria for SHAx states”, Emilio Martines, 3 Feb 2009

~12 cm helical shift of mag. axis

**Can VMEC produce such a state assuming fixed, axisymmetric outer boundary? YES**

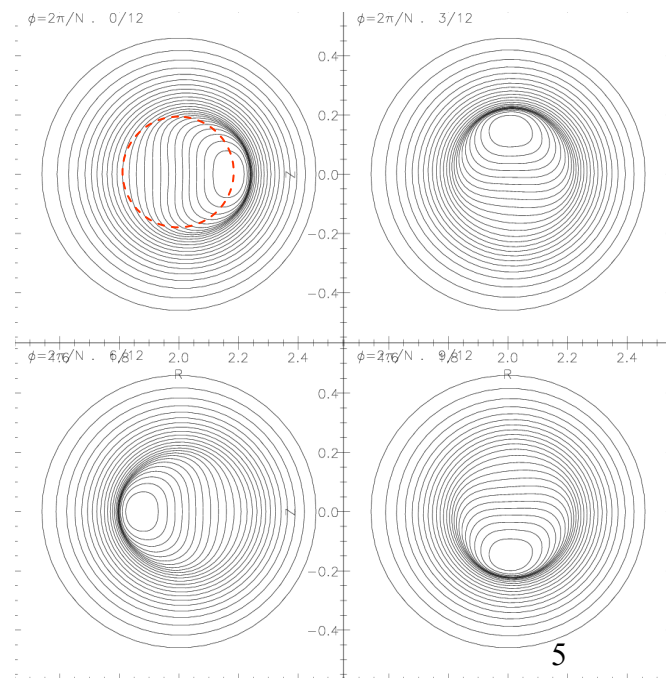
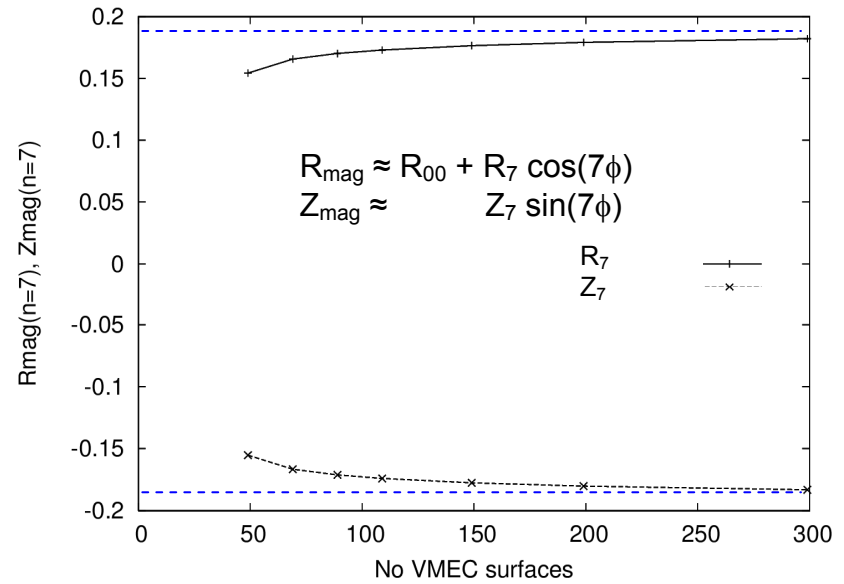
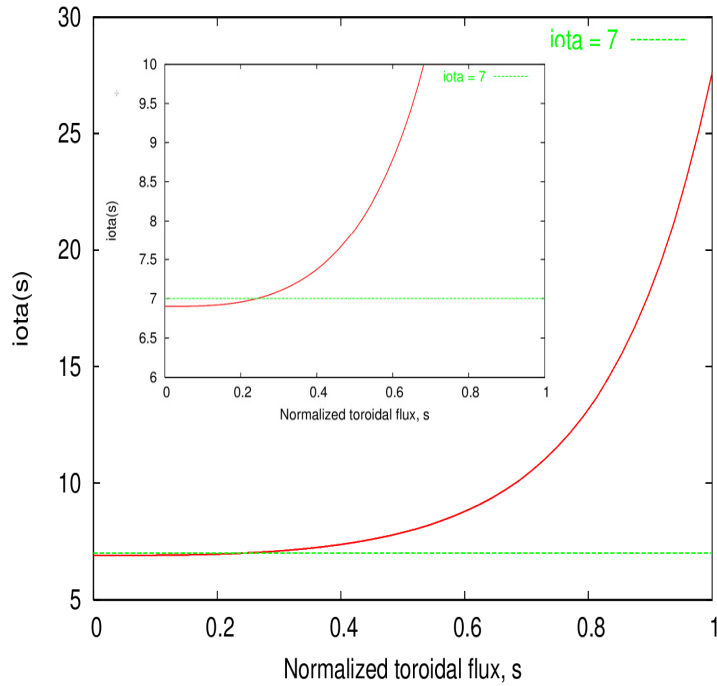
$$R = R_0 + a \cos(\theta), \quad Z = a \sin(\theta)$$

$$R_0 = 2.00\text{m}, \quad a = 0.46\text{m}$$

Assume monotonic  $\iota(s)$  with rational  $\iota=7$  at  $r/a \approx 0.5$  ( $s = 0.24$ );  $p(s)$

linear in  $s$

# VMEC input $\iota$ and convergence of mag axis



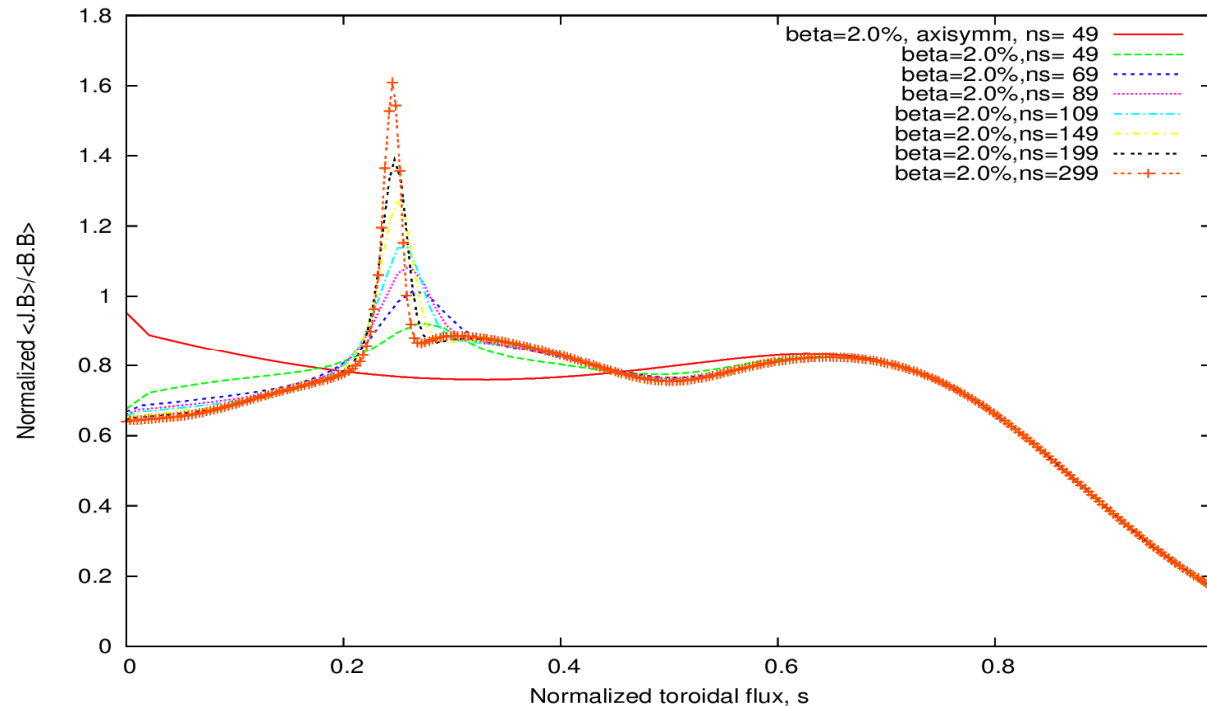
For given profiles, and  $\beta = 2\%$ , convergence to helical axis with shift  $\sim 18\text{cm}$

Final state robust to numerics

Axis shift depends on  $\beta$  and  $\iota'$

# VMEC equilibrium $k(s)$ profile

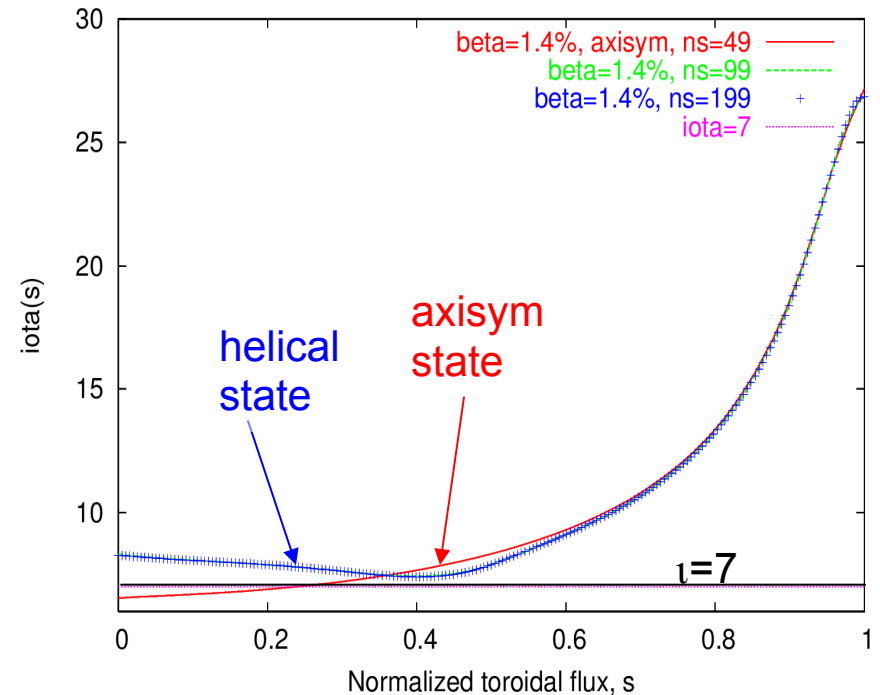
- essentially axisymmetric in outer region  $s > 0.7$  !!



- Recall - axisymmetric systems are not compatible with a toroidal loop voltage supporting the plasma current  $\Rightarrow$  edge region problematic
- So consider allowing the whole plasma current to be helical, rather than trying to maintain the plasma boundary axisymmetric?

## Similar story if supply initial $k(s)$ profile

- Choose  $k_0(s)$  to approx “fit” the  $k(s)$  output from previous case, but interpolating through peak at rational surface
- Adjust  $I_p$  so that  $\iota=7$  at  $s \approx 0.24$  for axisym equilibrium, as before.



- 3D helical states are formed, as before
- Now iota profile is modified by VMEC to AVOID passing through  $\iota=7$
- Again, little change (in  $\iota(s)$ ) from axisym profile for  $s > 0.7$  ( $r/a > 0.84$ )

# Use of helical fields to allow a long-pulse RFP

Phys Plas. 16, 022507 (2009) – current issue (Feb)

- Impose helical wobble of magnetic axis by applying external helical field, providing transform for reducing the required  $k$
- The helical field that reduces the required  $k$  is non-resonant, so good magnetic surfaces can be maintained

Assume fixed outer boundary shape with helical wobble of periodicity  $n$

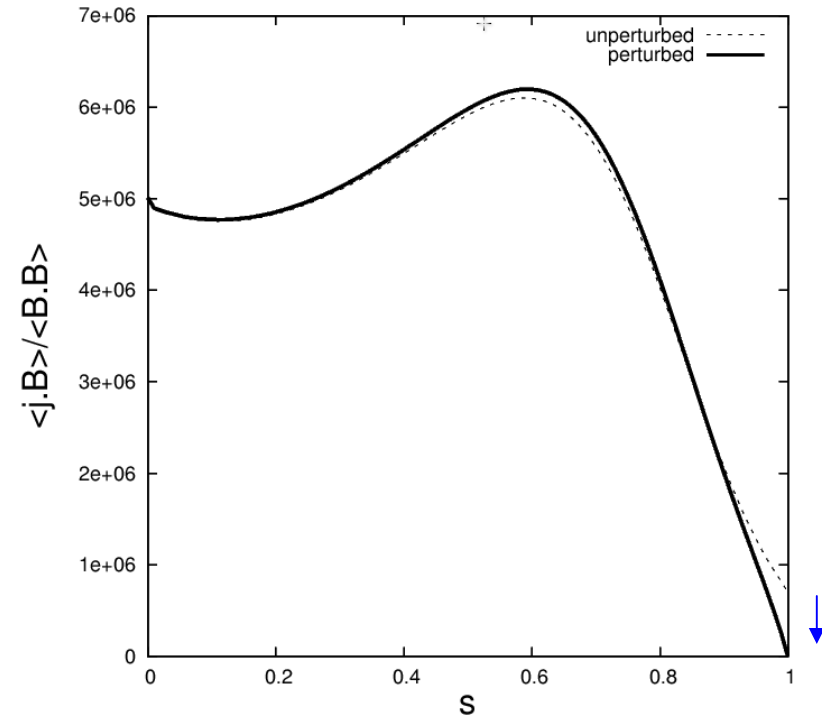
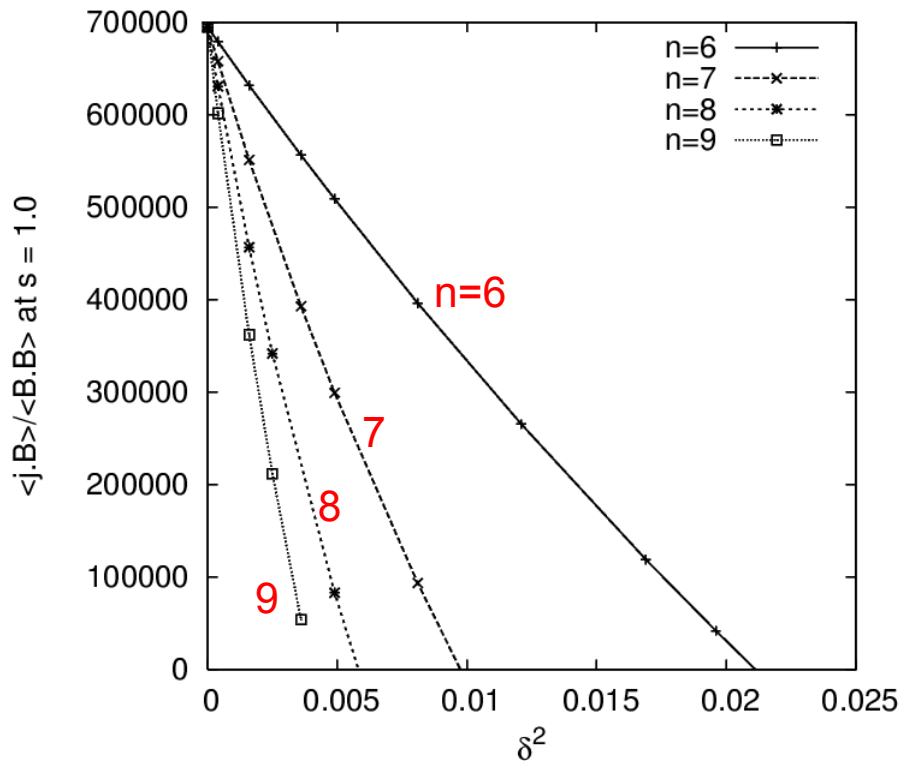
$$R(\theta, \phi) = R_{00} + a \cos \theta + \delta \cos n\phi, \quad Z(\theta, \phi) = a \sin \theta + \delta \sin n\phi; \quad R_{00} = 2.00\text{m}, \quad a = 0.46\text{m}$$

- Vary helical boundary wobble amplitude,  $\delta$ , until

$$k = \mu_0 \frac{\langle J \cdot B \rangle}{\langle B \cdot B \rangle} = \frac{\mu_0}{\eta B^2} \frac{V_t}{2\pi R} B_\phi = 0 \quad \text{at plasma edge, consistent with a}$$

current that can be maintained by a spatially constant  $V_t$

# VMEC Results – Required Helical Wobble

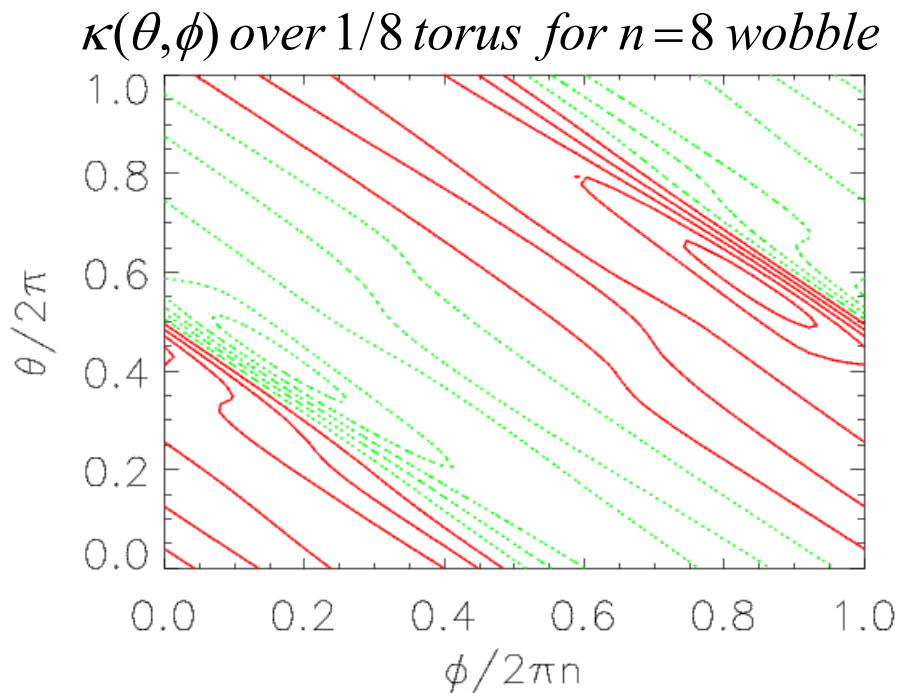


- Parallel current  $k(s)$  reduced at plasma edge as helical wobble is increased
- Approx scaling  $\Delta k(1) = n^4 \delta^2$

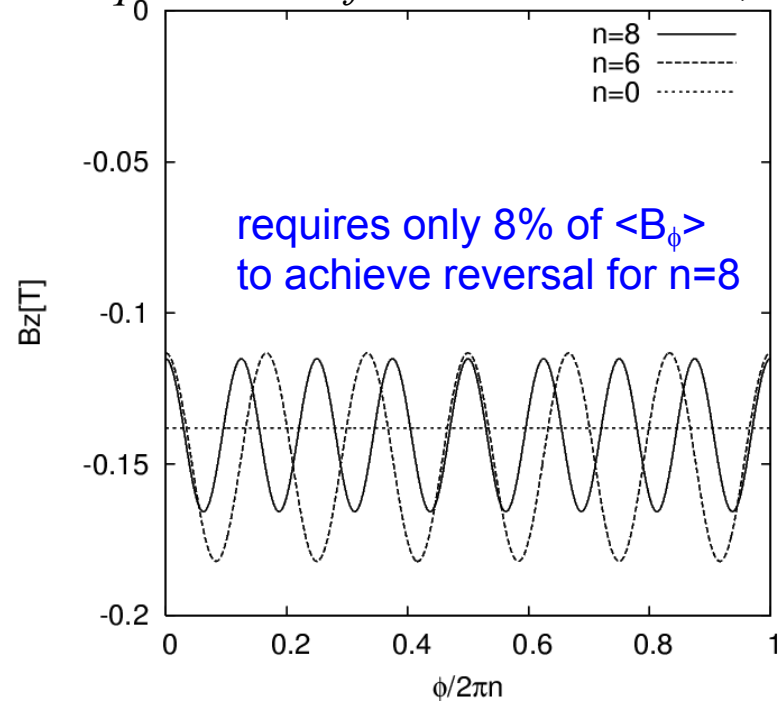
To determine the helical field coils must provide, use stellarator design tool NESCOIL (P. Merkel et al, Greifswald)

# NESCOIL results- Required Vertical Field from saddle coils on RFX

- NESCOIL determines the current distribution on a chosen coil surface s.t. the  $B_n$  from this distribution matches  $B_n$  from the plasma at the plasma boundary.  $\mathbf{j} = \delta(r - r_c) \nabla r \times \nabla \kappa(\theta, \phi)$



req'd vertical field around  $R=2m, Z=0m$



# RFX experiments

- RFX saddle coils can produce 0.04T of (n=8,m=1) helical field
- Experimental exploration of whether a toroidal loop voltage can maintain quiescent plasmas is within the RFX capability
- Preliminary experiments have commenced (March 2009), more are planned

# Conclusions

- Stellarator tools can contribute to analysis of SH states in RFP's and model potentially useful experiments
- Only a weak helical field is required to make  $k(r)$  zero at the edge so a spatially constant loop voltage can maintain an RFP
- RFX has already (this month) performed preliminary experiments applying  $m=1, n=7$  fields (so far, after  $q$  reversal) and will continue.
- The external field can (future) be chosen to ensure good neoclassical confinement (quasi-axisymmetry)
- The external helical + axisymmetric shaping fields can be optimized for MHD stability
- STELLOPT can be used as an optimization tool for RFP's