

# Weight growth due to resonant particles and a modified $\delta f$ method with smooth switching between $\delta f$ and total-f methods

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## Vlasov-Maxwell system and particle simulation

$$\frac{df}{dt} = \left\{ \frac{\partial}{\partial t} + \mathbf{v} \cdot \frac{\partial}{\partial \mathbf{x}} + \left[ \mathbf{F}_{ext} + q \left( \mathbf{E} + \frac{\mathbf{v} \times \mathbf{B}}{c} \right) \cdot \frac{\partial}{\partial \mathbf{p}} \right] \right\} f(\mathbf{x}, \mathbf{p}, t) = 0$$

$$\nabla \times \mathbf{B} = \frac{4\pi}{c} \int d^3 p \ q \mathbf{v} f(\mathbf{x}, \mathbf{p}, t) + \frac{1}{c} \frac{\partial \mathbf{E}}{\partial t}$$

$$\nabla \times \mathbf{E} = -\frac{1}{c} \frac{\partial \mathbf{B}}{\partial t},$$

$$\nabla \cdot \mathbf{E} = 4\pi \int d^3 p \ q f(\mathbf{x}, \mathbf{p}, t)$$

$$\nabla \cdot \mathbf{B} = 0$$

Nonlinear,  
differential-integral

- Particle-in-cell simulation -- effective solution method.
- Difficulty -- simulation noise.

$$\frac{\tilde{f}}{f} \sim \frac{1}{\sqrt{N}}$$

## $\delta f$ particle simulation method reduces noise

$$\begin{pmatrix} f \\ \mathbf{E} \\ \mathbf{B} \end{pmatrix} = \begin{pmatrix} f_0 \\ \mathbf{E}_0 \\ \mathbf{B}_0 \end{pmatrix} + \begin{pmatrix} \delta f \\ \delta \mathbf{E} \\ \delta \mathbf{B} \end{pmatrix}$$

A know solution;  
Control variates.

$$\begin{aligned} \frac{dw}{dt} &= \frac{1}{F} \frac{df_0}{dt} = \frac{q}{m} \left( \delta \mathbf{E} + \frac{\mathbf{v} \times \delta \mathbf{B}}{c} \right) \cdot \frac{1}{F} \frac{\partial f_0}{\partial \mathbf{v}} \\ &= \frac{w - g}{f_0} \frac{df_0}{dt} = \frac{q}{m} \left( \delta \mathbf{E} + \frac{\mathbf{v} \times \delta \mathbf{B}}{c} \right) \cdot \frac{(w - g)}{f_0} \frac{\partial f_0}{\partial \mathbf{v}} \end{aligned}$$

$$\delta f = \dot{w} F$$

$$\nabla \times \delta \mathbf{B} = \frac{4\pi}{c} \int d^3 p \, q \mathbf{v} \delta f(\mathbf{x}, \mathbf{p}, t) + \frac{1}{c} \frac{\partial \delta \mathbf{E}}{\partial t}$$

$$\nabla \times \delta \mathbf{E} = -\frac{1}{c} \frac{\partial \delta \mathbf{B}}{\partial t}$$

$$\nabla \cdot \delta \mathbf{E} = 4\pi \int d^3 p \, q \delta f(\mathbf{x}, \mathbf{p}, t)$$

$$\nabla \cdot \delta \mathbf{B} = 0$$

simulation particle distribuion  
 $F = g f$ ,  $g = \text{const}$ ;  
importance sampling

$$\frac{\tilde{f}}{f} \sim \frac{\tilde{\delta f}}{\delta f} \sim \frac{w}{\sqrt{N}} \ll \frac{1}{\sqrt{N}}, \text{ if } w \ll 1.$$

## Weight growth due to resonant simulation particles

$$\frac{\tilde{f}}{f} \sim \frac{\delta \tilde{f}}{f} \sim \frac{w}{\sqrt{N}} \gg \frac{1}{\sqrt{N}}, \text{ if } w \gg 1.$$

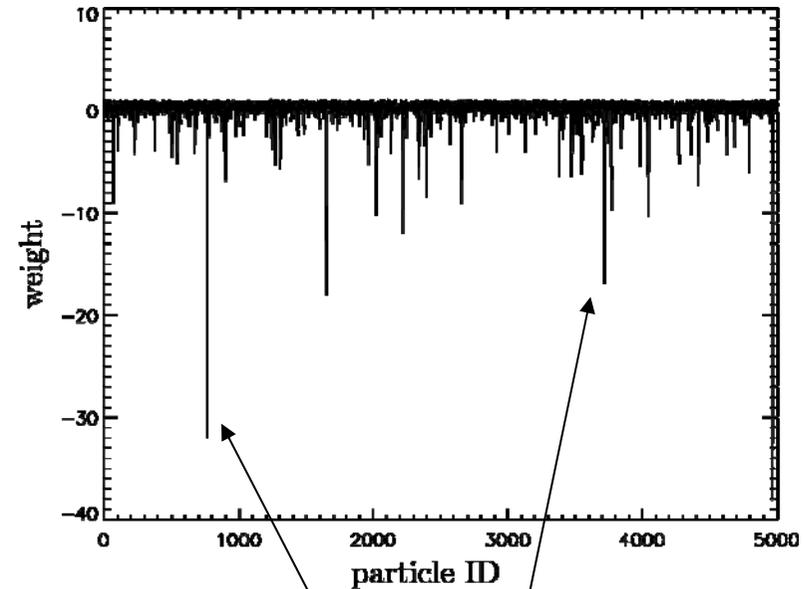
Can happen for many reasons.

$$f_0 = \frac{n_0(\mathbf{x})}{(2\pi T / m)^{3/2}} \exp\left(-\frac{v^2}{2T / m}\right)$$

$$\frac{d}{dt} \ln(1 - w) = \frac{q}{T} \delta \mathbf{E} \cdot \mathbf{v}$$

$$w(t) = 1 - [1 - w(t=0)] \exp[h(t)]$$

$$h(t) = -\int_0^t \frac{q \delta \mathbf{E} \cdot \mathbf{v}}{T} dt$$



$q \delta \mathbf{E} \cdot \mathbf{v} < 0$  for all  $t \Rightarrow w \rightarrow -\infty$

## Modified $\delta f$ method with smooth switching between $\delta f$ and total-f methods

$$f = \alpha f_0 + wF$$

$$\delta f = (\alpha - 1) f_0 + wF$$

$0 \leq \alpha \leq 1$   
 $\alpha = 0$  : total-f  
 $\alpha = 1$  :  $\delta f$

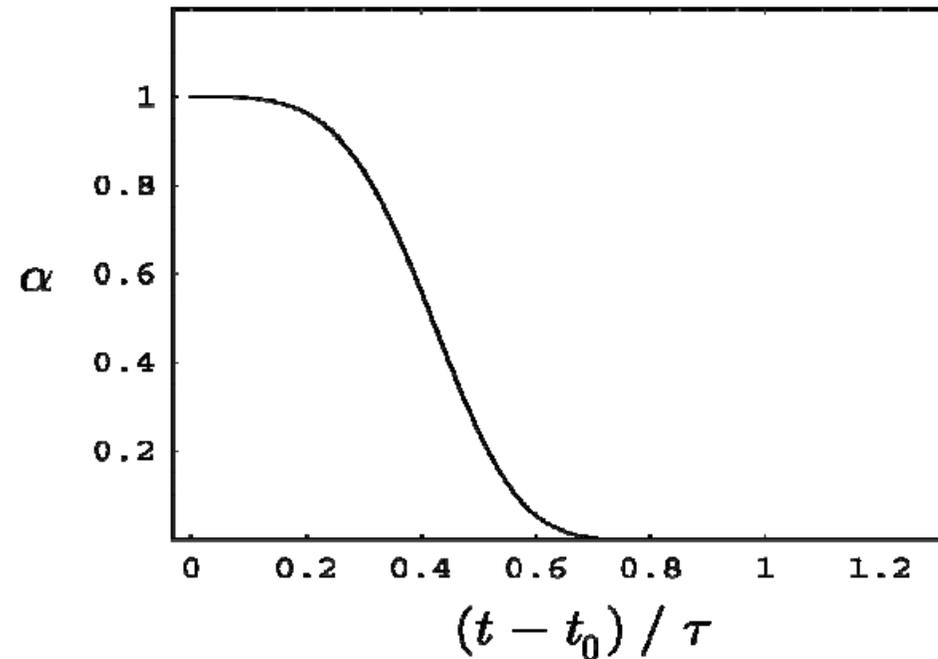
select the switching  
function  $0 \leq \alpha(t) \leq 1$

$$\begin{aligned} \frac{dw}{dt} &= \frac{w - g}{f_0} \frac{df_0}{dt} + \frac{w - g}{\alpha} \frac{d\alpha}{dt} \\ &= \frac{q}{m} \left( \delta \mathbf{E} + \frac{\mathbf{v} \times \delta \mathbf{B}}{c} \right) \cdot \frac{(w - g)}{f_0} \frac{\partial f_0}{\partial \mathbf{v}} + \frac{w - g}{\alpha} \frac{d\alpha}{dt} \end{aligned}$$

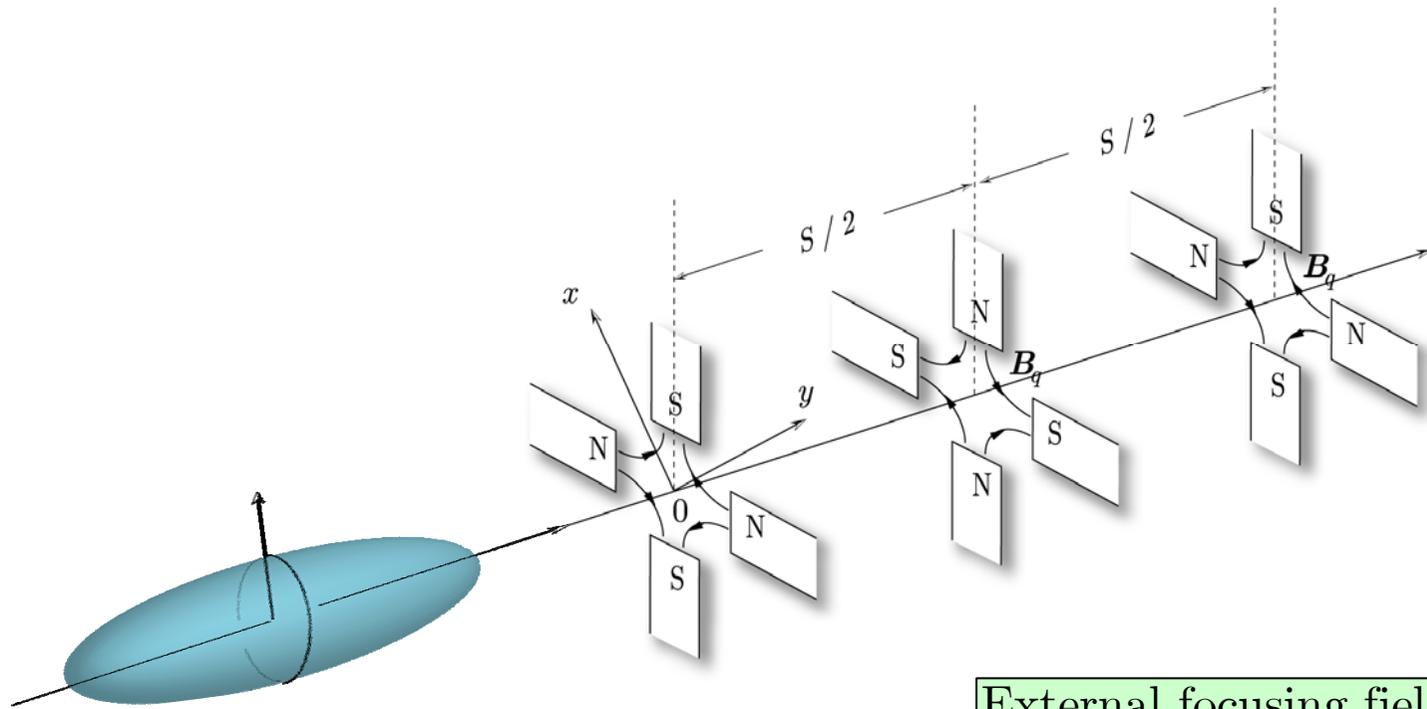
$\alpha$  can depend on  $(\mathbf{x}, \mathbf{v})$  too.

## Modified $\delta f$ method with smooth switching between $\delta f$ and total-f methods

$$\frac{d \ln \alpha}{dt} = \begin{cases} 0, & t - t_0 < 0, \\ -a \left( \frac{t - t_0}{\tau} \right)^n, & 0 \leq t - t_0 < \tau, \\ -a, & \tau < t - t_0, \end{cases}$$



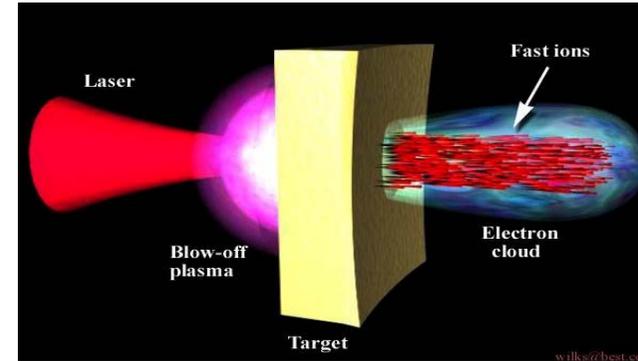
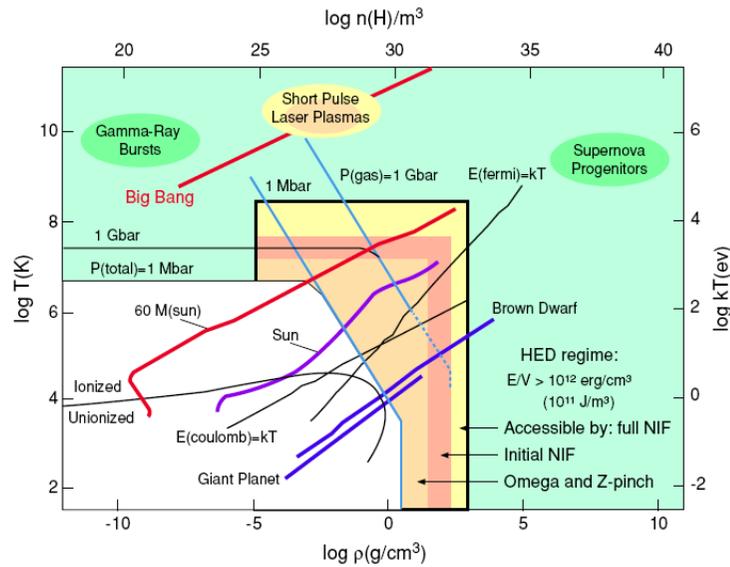
## Vlasov-Maxwell system for high intensity particle beams



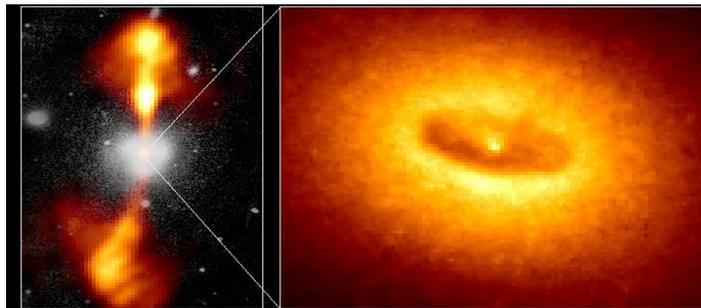
External focusing field:  
$$\mathbf{F}_{foc} = -m_b \omega_{\beta b}^2 \mathbf{x}_{\perp}$$

*An Introduction to the Physics of Intense Charged Particle Beams in High Energy Accelerators*, R. C. Davidson and H. Qin, World Scientific (2001)

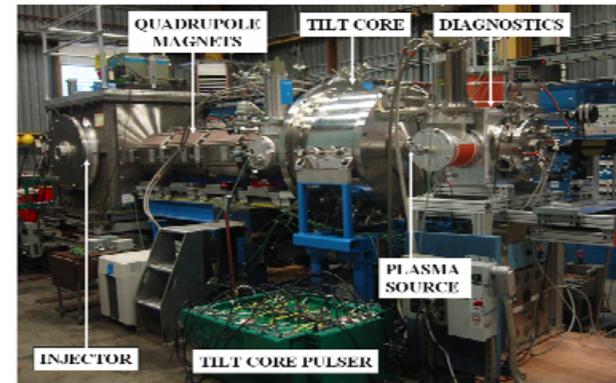
# Beam physics application --- high energy density physics



Gamma ray bursters experiment

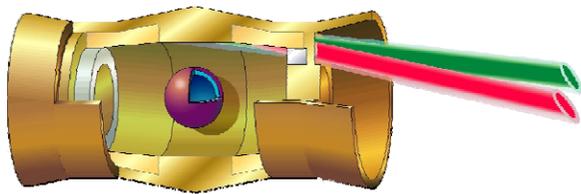
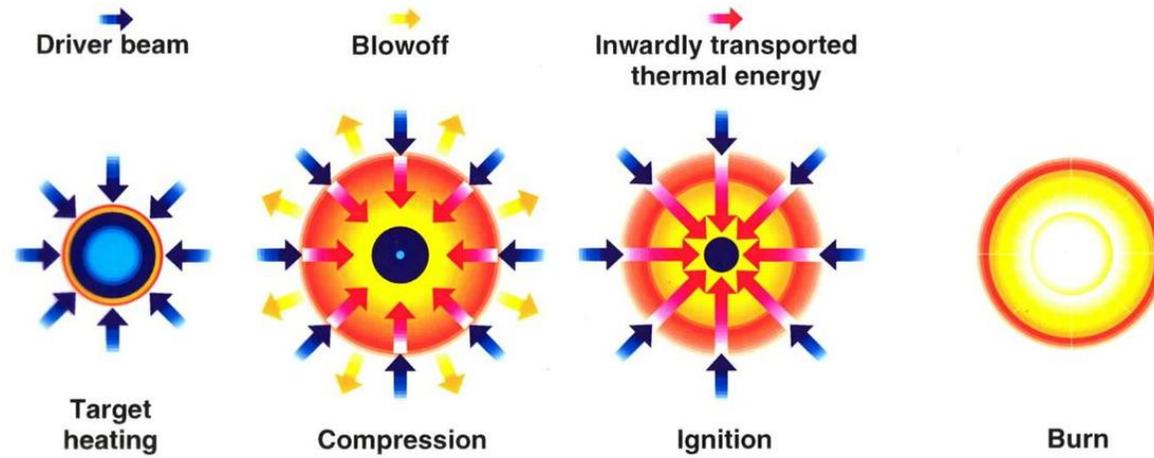


Photoionized plasmas in an accreting massive black hole

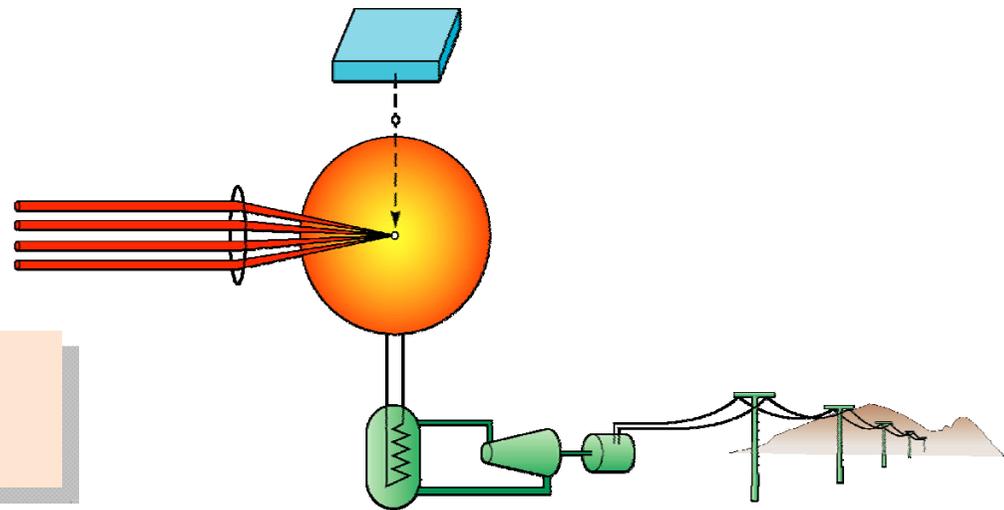


Neutralized drift compression experiment for ion beam driven HEDP

## Beam physics application --- heavy ion fusion



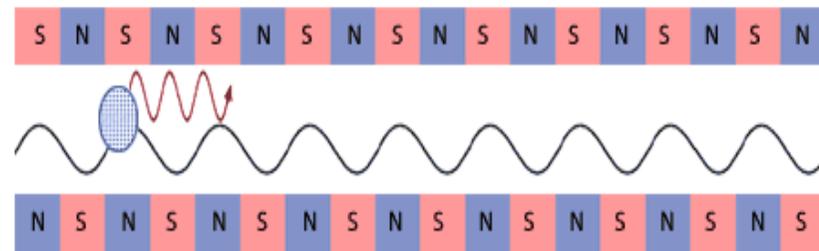
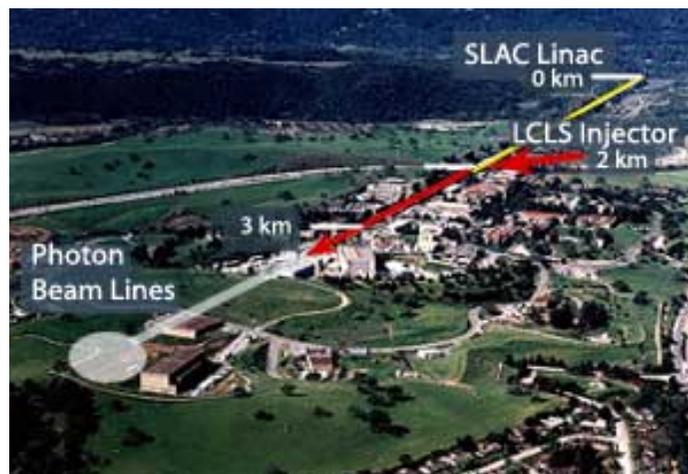
Beams strike "hohlraum," producing x-ray bath for fusion capsules.



# Beam physics application --- modern high intensity accelerators



Spallation Neutron Source



Linear Coherent Light Source

## Collective instabilities in intense charged particle beams

### One-Component Beams

- Harris and Weibel instability driven by temperature anisotropy

$$T_{\perp} \gg T_{\parallel} .$$

- Resistive wall instability

### Propagation Through Background species

- Two-stream instability
- Ion-electron (Electron cloud) instability

### Propagation Through Background Plasma

- Resistive hose instability
- Multispecies Weibel instability
- Multispecies two-stream instability

# Beam Equilibrium Stability and Transport (BEST) Code

## Physics

- ❑ Perturbative particle simulation method to reduce noise.
- ❑ Linear eigenmodes and nonlinear evolution.
- ❑ 2D and 3D equilibrium structure.
- ❑ Multi-species; electrons and ions; accommodate very large mass ratio.
- ❑ Multi-time-scales, frequency span a factor of  $10^5$ .
- ❑ 3D nonlinear perturbation.

## Computation

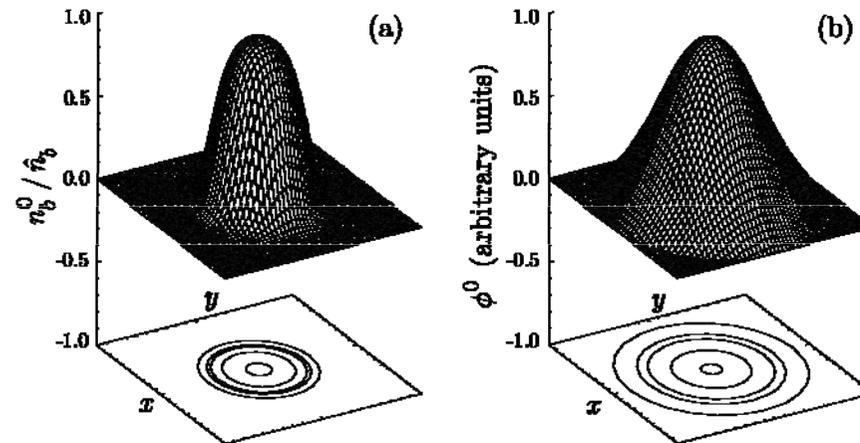
- ❑ Message Passing Interface
  - Multiple-1D domain decomposition (OpenMP by users).
- ❑ Large-scale computing: particle x time-steps  $\sim 0.5 \times 10^{12}$ .
- ❑ Scales linearly to 512 processors on IBM-SP3 at NERSC.
- ❑ NetCDF, HDF5 parallel I/O diagnostics.

## Energy anisotropic coasting beams

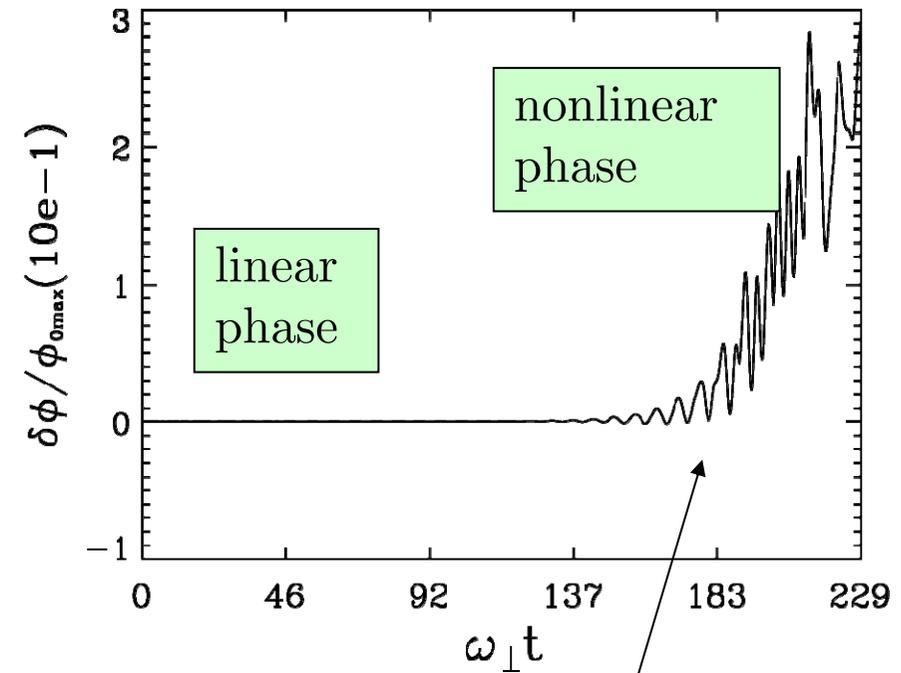
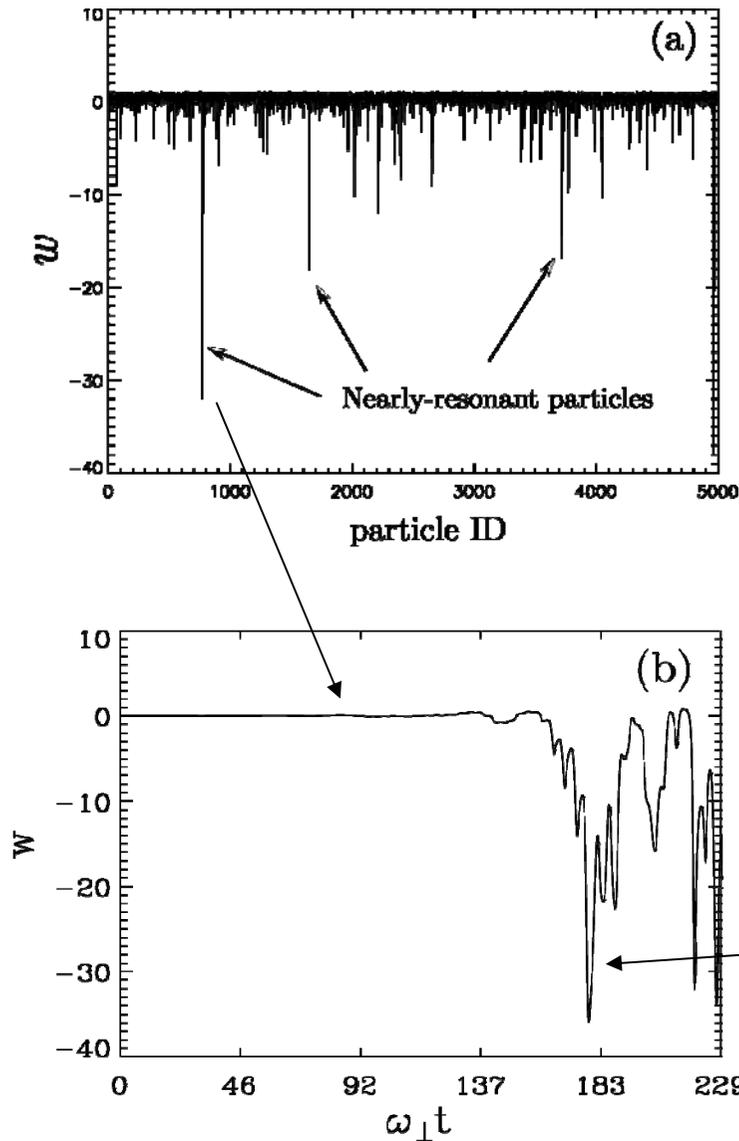
$$f_0 = \frac{\hat{n}}{(2\pi m T_\perp)(2\pi m T_z)^{1/2}} \exp\left(-\frac{H_\perp}{T_\perp} - \frac{H_z}{T_z}\right)$$

$$H_z = \frac{p_z^2}{2m}, \quad H_\perp = \frac{p_\perp^2}{2m} + \frac{m}{2}\omega_\beta^2 r^2 + e\phi_0(z)$$

$$\nabla^2 \phi_0 = -4\pi e \hat{n} \exp\left[-\frac{m\omega_\beta^2 r^2 + 2e\phi_0(r)}{2T_\perp}\right]$$

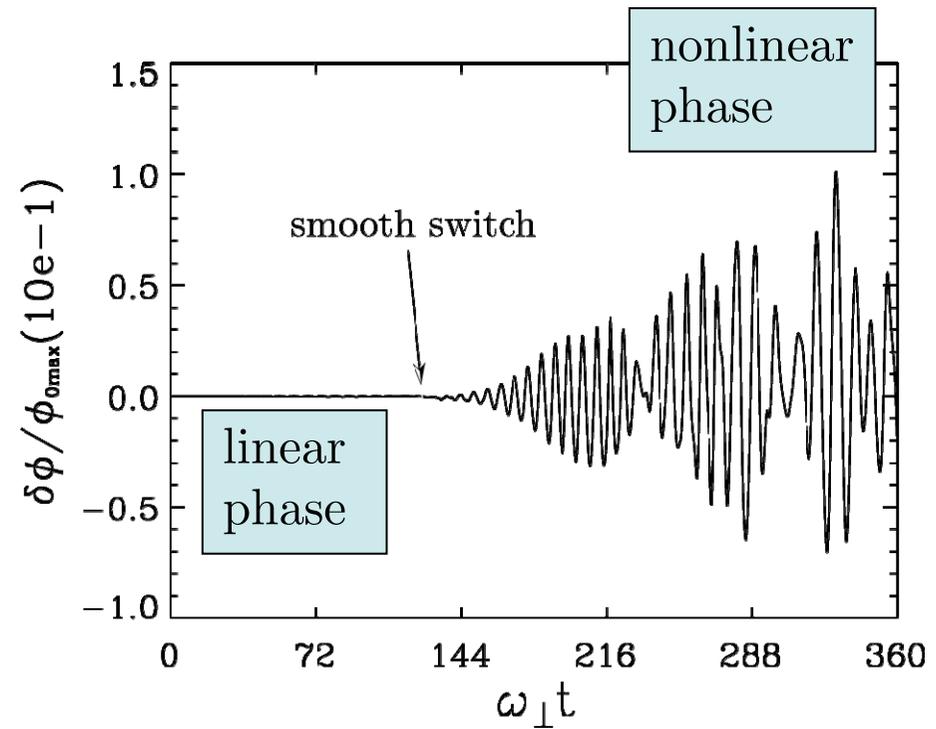
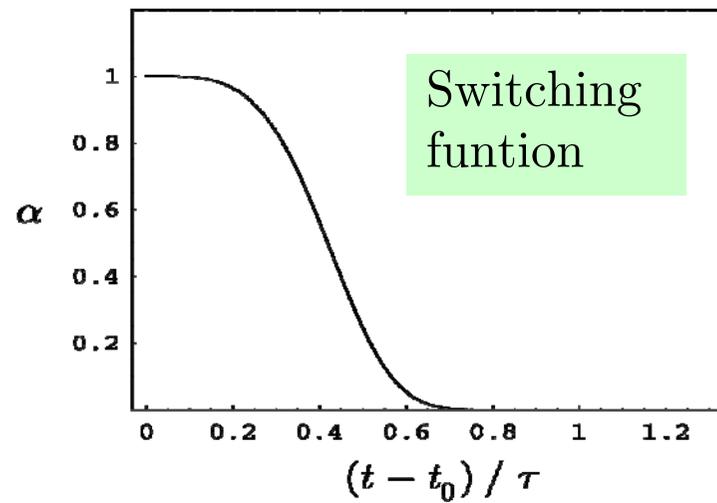
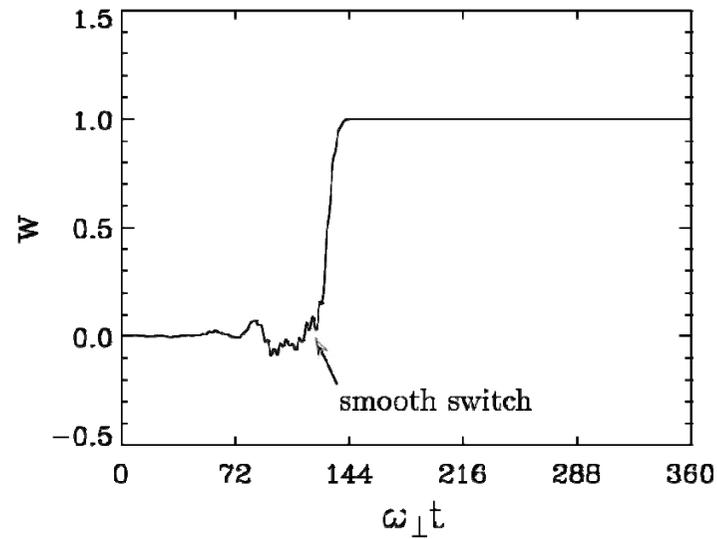


# Temperature anisotropy instability with delta-f method



Simulation is dominated by large local error field.

## Valid simulation result by the smooth switching algorithm



## Conclusions

- ❑ Nonlinear  $\delta f$  particle simulation method significantly reduces noise.
- ❑ Resonant simulation particles induce large weight growth.
- ❑ A modified  $\delta f$  method with smooth switching between  $\delta f$  and total-f methods is developed.